



Module Assembly at Wuhan

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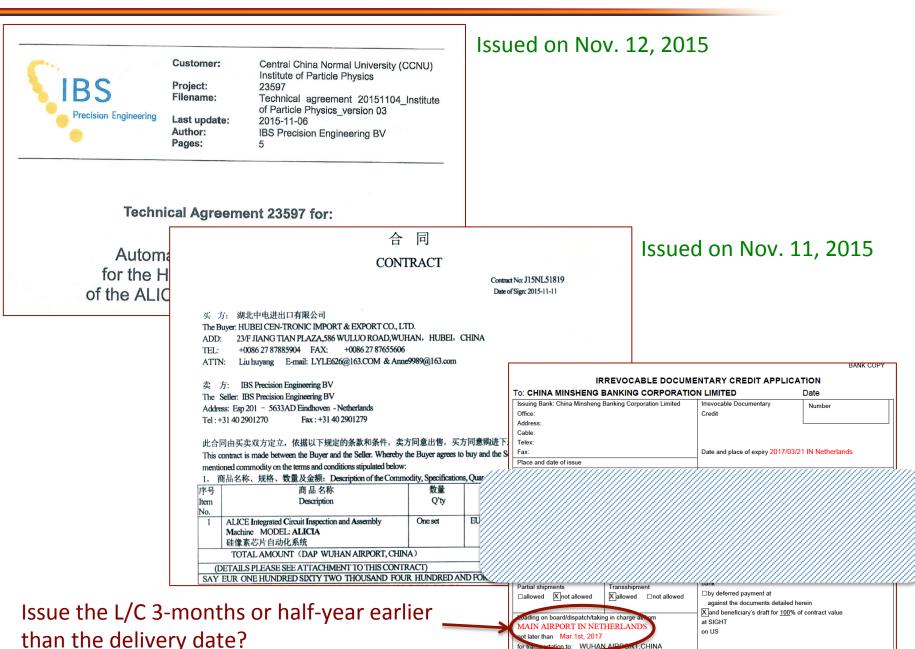
Outline

- Overview of Wuhan status
- Lab preparations
- R&D activities at Wuhan
 - Vision control software
 - Chip-FPC interconnections
- Plan at Wuhan

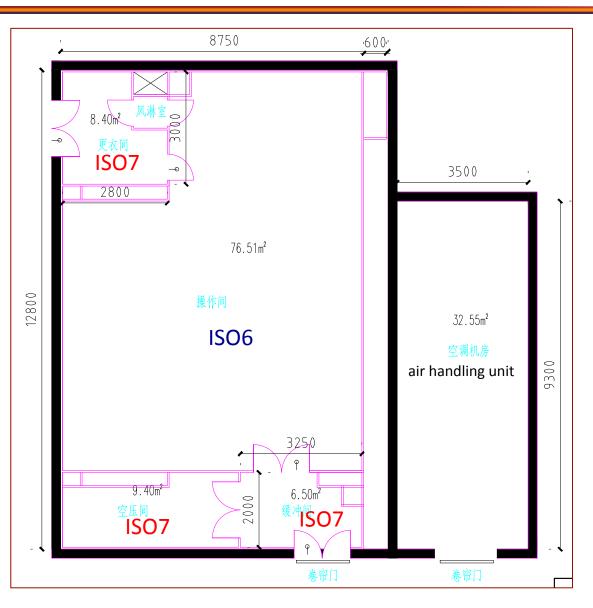
Overview of Wuhan status

- Application to import the baseline HIC machine was approved by MOE and MOF in end of July, 2015, and the budget is available by the support of CCNU.
- Technical agreement was signed between CCNU and IBS in November, 2015.
- Contract was signed by IBS and CCNU representative trade company in November, 2015.
- Clean room preparation at ISO6 level was approved by CCNU in November, and is under the phase of inviting tenders.
- A phD student, Chaosong Gao, has been working on chip design at CERN since
 2013. Ping Yang was back to CCNU in 2015.
- A phD student, Mangmang An has been starting the chip testing and assembly training at CERN since this November.
- R&D activities on the module assembly system are on-going as planed.

Overview of Wuhan status – HIC machine procurement



Lab preparations



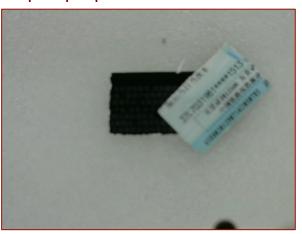
Clean room design plan

- Construction of clean room was approved by CCNU this November, and budget is available.
- 2. Inviting for tenders in December
- 3. Design requirements:
 - Ground floor, vehicle access
 - Clean level: ISO6 (1000)
 - Total area: 110 m²
 - ➤ ISO6 level area: ~ 75 m² operation area
 - ▶ ISO7 level area: ~ 35 m² (8 m² locker room including air shower + 9 m² air compressing room + 6 m² buffer area)
 - Controllable temperature: 20±2 °C
 - Humidity: 45%±15%
 - ESD flooring or conductive PVC flooring
 - Noise level ≤ 60 dB

R&D activities at Wuhan – Vision control software

- Image contour matching algorithm was developed to control the test stand automatically in X/Y/Z/φ dimensions.
- Matching precision at one-pixel level

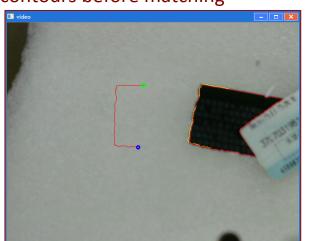
Step 1: prepare reference scene



Step 2: marker a feature contour



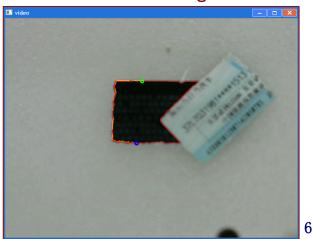
Step 3: recognized feature contours before matching



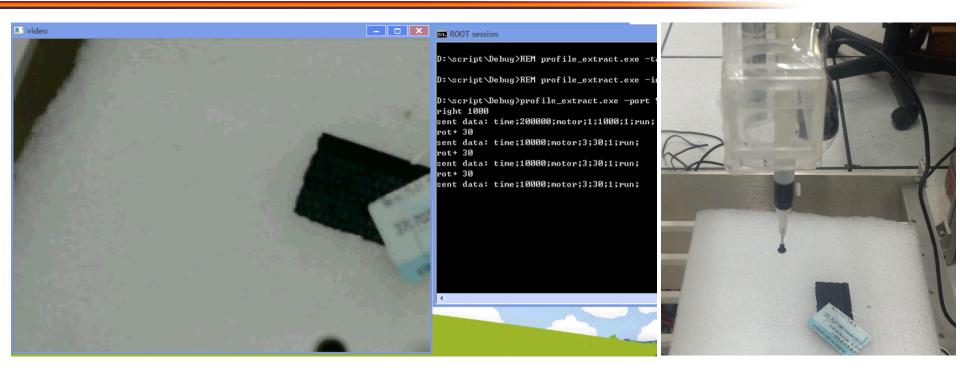
Step 4: Automatically matching



Step 5: recognized feature contours after matching



R&D activities at Wuhan – Vision control software



Script: mc.txt

setOrgFile test.bmp //specify the reference scene picture
setModFile mod.bmp //specify the updated reference scene with highlighted feature contour
matchFeatureToCamera 0 0 0 //set the desired position (X/Y/Z) compared to the reference scene

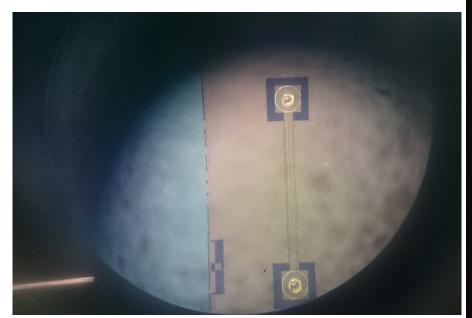
R&D activities at Wuhan – Chip-FPC interconnections

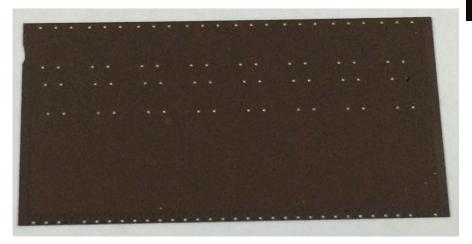
Step 1: mount ball on chip Gold wire (~25 um) Mounted gold ball (~50 um) **FPC** FPC ball mounter machine Chip pad chip

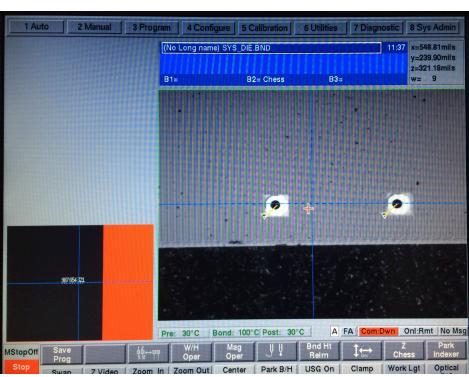


R&D activities at Wuhan – Chip-FPC interconnections

Step 1: mount ball on chip





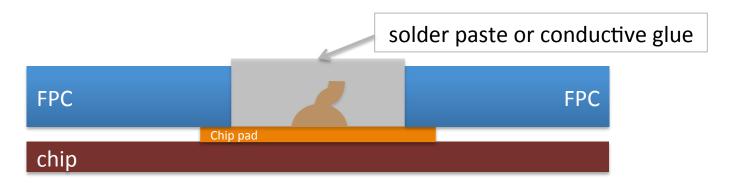


microscope picture

R&D activities at Wuhan – Chip-FPC interconnections

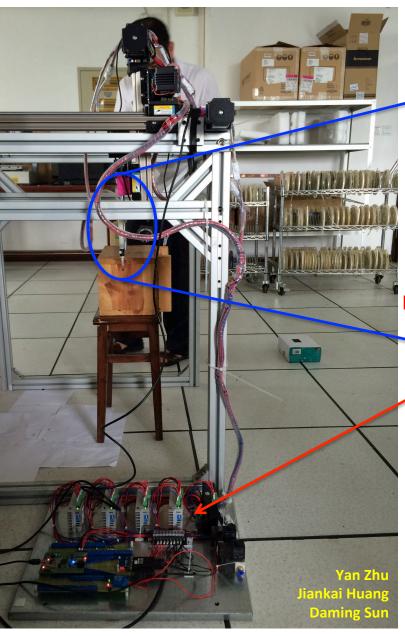
Step 2: chip placement on FPC (compatible to HIC assembly machine)

Step 3: fill FPC vias with solder paste or conductive glue by automatic dispenser machine

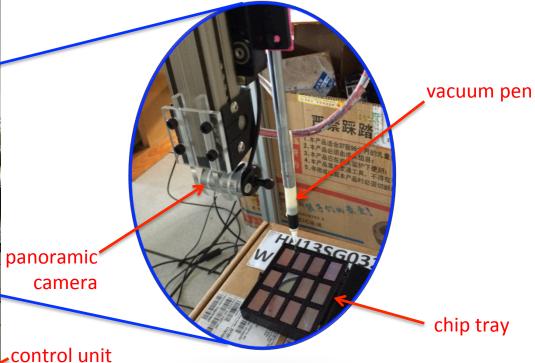


Thanks for your attention!

Activities at Wuhan - R & D on Vision Control System



Custom designed test stand:



- Automated video system: edge tracking
- Automated software-based shape analysis
- Fully programmable interface (PC)
- Wide travel range in XYZ, and rotatable in XY plane
- ~100 macrons XYZ scale resolution
- Binocular to be installed close to vacuum pen to determine distance to object in Z direction

Manpower preparations

- Mangmang An (phD student, module assembly training at CERN)
- Chaosong Gao (phD student, chip design at CERN)
- Jiankai Huang (Master student, automatic assembly machine R&D)
- Jun Liu (electronic technician)
- Daming Sun (Machining engineer)
- Xiangming Sun
- Yaping Wang
- Yan Zhu (Master student, vision control software R&D)